ABSTRACT

A method for processing error control for a seeking servo of an optical disk drive includes calculating a "track on" time when control of a pickup head is switched from a

5   seeking servo system to a tracking servo system to start a "track on" process, moving the pickup head to the center of a movable range when the "track on" process is not completed in a predetermined time, and switching control of the pickup head to the tracking servo system to start another "track on" process.

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